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ON TEACHING STUDENTS NEWTON'S METHOD OF SOLVING ONE-DIMENSIONAL OPTIMIZATION PROBLEMS

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Abstract ARTICLEINFO

We know that optimization is the selection of the best available options to achieve the highest efficiency in a process. One-dimensional optimization, that is, one-variable function optimization, is one of the simplest cases of optimization problems. Even so, such issues occupy an important place in the theory of optimization. The reason is that one-dimensional optimization problems are often encountered in engineering practice and are also widely used in complex multi-dimensional optimization problems.

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To solve the optimization problems, the steps are performed in the following sequence. let's say f(x) let the function be twice differentiable. As we know, the minimum condition of such a function:

$$f'(x^*) = 0$$

and this is a necessary condition. x^* - and for the point to be the minimum point:

$$f''(x^*) > 0$$

a condition is a sufficient condition.

So, $f'(x^*) = 0$ we solve the equation numerically. We give the initial approximation of xk, and we approximate the solution ourselves. We expand the function at this point into a Taylor series. In this case, we limit ourselves to the second-order term, that is, we build a quadratic model of the function.

$$f(x) \approx \bar{f}(x) = f(x_k) + f'(x_k)(x - x_k)$$

If $f''(x_k) \neq 0$ if so, then f(x) has a single stationary point. To find this point $\hat{f}'(x)$ – we make the derivative equal to zero:

$$f'(x) = 0; \hat{f}'(x) = \left(f(x_k) + f'(x_k)(x - x_k) + \frac{1}{2!}(f''(x_k)(x - x_k)^2)\right)' = 0$$

$$=> 0 + f'(x_k) + \frac{1}{2} * 2 * f''(x_k)(x - x_k) = 0 =>$$

 $x = x_k - \frac{f'(x_k)}{f''(x_k)}$ find the solution to the minimum of x k+1 - we accept as approximation, as a result we have the following iterative formula:

$$x_{k+1} = x_k - \frac{f'(x_k)}{f''(x_k)}$$
 (*)

This formula is the same used to solve the equation f(x)=0

$$x_{k+1} = x_k - \frac{f(x_k)}{f'(x_k)}$$

It should be noted that it is similar to the formula of Newton's method, but differs from it.

- 1) f'(x) = 0 the equation can determine not only the minimum, but also the maximum point.
- 2) $\hat{f}(x)$ the model function may differ greatly from the function f(x) being optimized

That is why at every step to check that we are going to the minimum $f(x_{k+1}) < f(x_k)$ we need to check the condition. If this condition is met, then we will proceed to the next step. If $f(x_{k+1}) < f(x_k)$ and $f'(x)(x - x_k) = f(x_k)$ x_k < 0 is, then f(x) must decrease from x_k in the direction of x_{k+1} at the beginning of the function. Therefore, the next optimal point can be found by dividing the step in the opposite direction, for example:

$$x'_{k+1} = \frac{x_{k+1} + x_k}{2}$$

as can be seen from the formula (*), $f'(x_k)(x-x_k)$ the expression is negative if and only if $f''(x_k)>0$. This means that if the local model used to derive the Newton step has a minimum (not a maximum), then the step is guaranteed to have an optimal direction.

If on the other hand, if f''(x) < 0 and $f'(x_k)(x - x_k) > 0$, then f(x) increases initially when going from x_k to x_{k+1} , so the step should be done in the opposite direction.

As a criterion for stopping iteration (convergence) in optimization.

$$\left| \frac{f'(x_{k+1})}{f(x_k)} \right| < \varepsilon$$

the condition can be accepted, ε - pre-given precision. This method is called Newton or Newton-Raphson method. In some cases f(x) it is difficult to get derivatives of the function, in such cases Newton's method can be modified. For this, we choose initial approximation x_k and step h. x_k -h, x_k , x_k +h let's look at the points. In that case $f'(x_k)$ va $f''(x_k)$ derivatives can be replaced by approximate formulas as follows.

$$f'(x) = \lim_{h \to 0} \frac{f(x+h) - f(x)}{h}$$
 or $f'(x) = \lim_{h \to 0} \frac{f(x+h) - f(x-h)}{2h}$

lim dropping the symbols, we get the following approximate formulas

$$f'(x_k) \approx \frac{f(x_k+h) - f(x_k-h)}{2h};$$

$$f''(x_k) \approx \frac{f'(x_k+h) - f'(x_k-h)}{2h} = \frac{\frac{f(x_k+h) - f(x_k)}{h} - \frac{f(x_k) - f(x_k-h)}{h}}{2h} = >$$

$$f''(x_k) \approx \frac{f(x_k+h) - 2f(x_k) + f(x_k-h)}{2h^2}.$$

In that case, if we put (*) in the above formula, we will get an iterative formula as a result:

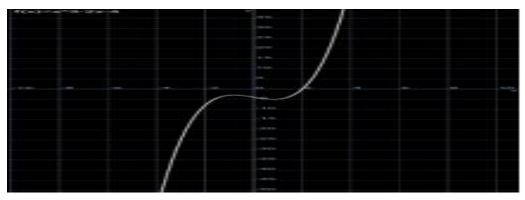
$$x_{k+1} = x_k - \frac{f(x_k+h) - f(x_k-h)}{f(x_k+h) - 2f(x_k) + f(x_k-h)} *h$$

This formula is called Quasi Newton or Newton's modified method.

Let's look at the following examples:

1)
$$f(x) = x^3 - 2x - 4$$

 x_1 we look at the graph of the function to pick a point. As can be seen from the graph, the minimum point is close to the point x=1. That is



 $x_1 = 1$ we choose that. Using the above formulas successively, we find the solution with the given accuracy. We use the Excel program to facilitate calculations:

x_k	Values	$f'(x_k)$	$f''(x_k)$	$f(x_k)$?	$f(x_{k+1})$	$\left \frac{f'(x_{k+1})}{f(x_k)}\right < 0.001$
x_1	1	1	6	-5	>	-5,087962963	0,016666667
x_2	0,833333333	0,083333333	5	-5,087962963	>	-5,088662037	0,000163785
<i>x</i> ₃	0,816666667	0,000833333	4,9	-5,088662037	>	-5,088662108	1,70515E-08

Since we selected a point x_1 using the graph, the solution was found in the second step. x_1 the number of steps may increase when we choose a point arbitrarily.

2) Let's look at the graph of the following $f(x) = x^4 - \ln(x) + 4$. We find the first and second derivatives of the function:

$$f^{'}(x)=4x^3-rac{1}{x}; \quad f^{''}(x)=12x^2+rac{1}{x^2}$$

Using the graph, we select the point x_1 =0,7. x_1 since we chose a point very close to the exact solution, the solution was found in two steps with the given accuracy.

x_k	Values	$f'(x_k)$	$f''(x_k)$	$f(x_k)$?	$f(x_{k+1})$	$\left \frac{f'(x_{k+1})}{f(x_k)} \right < 0.001$
x_1	0,7	-0,056571429	7,920816327	4,596774944	>	4,596573595	6,15052E-05
x_2	0,707142121	0,000282726	8,000399854	4,596573595	>	4,59657359	1,53706E-09

Newton's method used to solve optimization problems has the following disadvantages:

- 1) The method requires a sufficiently good initial approximation, otherwise the number of steps will increase, that is, the selected point may have a large difference in the minimum of the function f(x) being optimized
- 2) It requires the existence and analyticity of first and second order derivatives.
- 3) In Newton's method, there is no obstacle that prevents the iterative method from going towards maximum or turning points instead of the required minimum point. Also, the possibility that the step x_{k+1} - x_k is too large can be shown as a disadvantage.

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