

Stress-strain state of thick shells of variable thickness

Gaffarov H. R., Karimov A. O.

Bukhara Institute of engineering and technology, Bukhara. Republic of Uzbekistan.

ABSTRACT

This paper makes analyses of the stress-strain state of thick shells of variable thickness. On this case, research has been undergone from theoretical and methodological points as the whole. Outcomes and shortcomings were highlighted as conclusion of the research paper.

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1. INTRODUCTION

Consider a thick-walled cylindrical shell, the relative thickness of which is an arbitrary function of the axial coordinate α . Let the shell be under the action of axisymmetric surface forces applied to the outer side surface (figure 1). We assume that the loads have both a vertical P_γ and a horizontal P_α component.

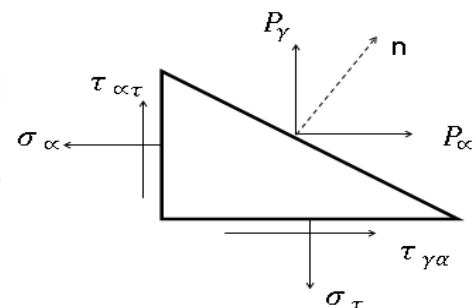
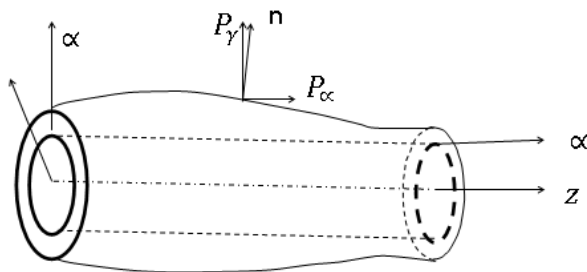


Figure 1

In addition, the inner surface of the shell is a circular cylindrical surface. The ends of the shell are free from loads (figure 2). As is known, stresses on an inclined platform are determined by the formulas:

$$P_\alpha = 6\alpha \cos(n, \alpha) + \tau \alpha \gamma \cos(n, \gamma) \quad (1)$$

$$P_\gamma = \tau \alpha \gamma \cos(n, \gamma) + 6\gamma \cos(n, \gamma)$$

Guide cosines in expressions (1) are determined by the following relations:

$$\cos(n, \alpha) = \frac{\frac{dh}{d\alpha}}{\sqrt{1 + \left(\frac{dh}{d\alpha}\right)^2}},$$

$$\cos(n, \gamma) = -\frac{1}{\sqrt{1 + \left(\frac{dh}{d\alpha}\right)^2}} \quad (2)$$

$$P_\alpha = 6\alpha \cos(n, \alpha) + \tau_{\alpha\gamma} \cos(n, \gamma) \quad (1) \quad P_\gamma$$

$$= \tau_{\alpha\gamma} \cos(n, \gamma) + 6\gamma \cos(n, \gamma) \quad \text{the}$$

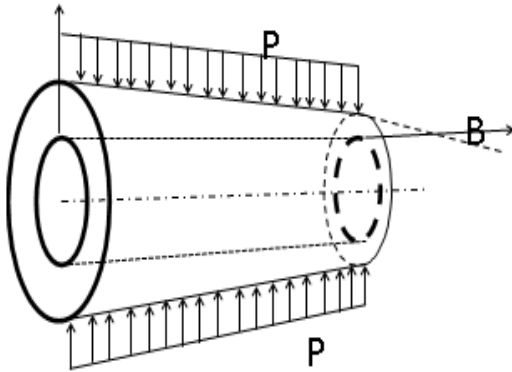


Figure 2

Then the equations (1) relating to the points of the boundary surface $h = h(\alpha)$ and being static conditions of equilibrium for this surface will take the form:

$$\left. \begin{aligned} P_\alpha &= \frac{1}{\sqrt{1 + \left(\frac{dh}{d\alpha}\right)^2}} \left(\frac{dh}{d\alpha} \sigma_\alpha - \tau_{\alpha\gamma} \right) \\ P_\gamma &= \frac{1}{\sqrt{1 + \left(\frac{dh}{d\alpha}\right)^2}} \left(\frac{dh}{d\alpha} \tau_{\alpha\gamma} - \sigma_\gamma \right) \end{aligned} \right\} \quad (3)$$

Voltage 6γ , $\tau_{\alpha\gamma}$ and 6α included in the formula (1) for internal points of the considered body are determined by the known ratio by the method of initial functions (MNF):

$$\left. \begin{aligned} \sigma_\gamma &= L_{31} U^0 + L_{32} W^0 + L_{33} \delta_\gamma^0 + L_{34} \tau_{\alpha\gamma}^0 \\ \tau_{\alpha\gamma} &= L_{41} U^0 + L_{42} W^0 + L_{43} \delta_\gamma^0 + L_{44} \tau_{\alpha\gamma}^0 \\ \sigma_\gamma &= L_{51} U^0 + L_{52} W^0 + L_{53} \delta_\gamma^0 + L_{54} \tau_{\alpha\gamma}^0 \end{aligned} \right\} \quad (4)$$

In this case, the relations (4) are significantly simplified, since $\sigma_\gamma^0 = \tau_{\alpha\gamma}^0 = 0$

Then get:

$$\left. \begin{aligned} \sigma_\gamma &= L_{31} U^0 + L_{32} W^0 \\ \tau_{\alpha\gamma} &= L_{41} U^0 + L_{42} W^0 \\ \sigma_\gamma &= L_{51} U^0 + L_{52} W^0 \end{aligned} \right\} \quad (5)$$

Substituting (5) in the system (3), we get:

$$\left. \begin{aligned} \sqrt{1 + \left(\frac{dh}{d\alpha}\right)^2} P_\alpha &= \frac{dh}{d\alpha} (L_{51}^{(h)} U^0 + L_{52}^{(h)} W^0) - (L_{41}^{(h)} U^0 + L_{42}^{(h)} W^0) \\ \sqrt{1 + \left(\frac{dh}{d\alpha}\right)^2} P_\gamma &= \frac{dh}{d\alpha} (L_{41}^{(h)} U^0 + L_{42}^{(h)} W^0) - (L_{31}^{(h)} U^0 + L_{32}^{(h)} W^0) \end{aligned} \right\} \quad (6)$$

In contrast to similar dependencies for shells of constant thickness, here the coefficients in the operators $L_{mn}(m=3,4,5; n=1,2)$ are functions of α .

In this regard, when performing the operator multiplication operation, the commutativity property is not observed, that is, for example:

$$L_{41}^{(h)} \cdot L_{42}^{(h)} \neq L_{42}^{(h)} \cdot L_{41}^{(h)}$$

Therefore, for problems of this class, it is impossible to introduce a resolving function in the same way as it was done in the case of shells of constant thickness. However, for some particular problems, such a function can be found. If we restrict ourselves to the first terms in the operators, then due to the linear dependence of some coefficients in the L_{mn} operators, we can find a resolving function for the shell with free ends.

In this case, the L_{mn} operators will look like:

$$\left. \begin{aligned} I_{31} &= a_{3(1)} \frac{d}{d\alpha} & I_{32} &= C_3(0) & I_{41} &= a_4(2) \frac{d^2}{d\alpha^2} \\ I_{42} &= C_4(1) \frac{d}{d\alpha} & I_{51} &= a_5(1) \frac{d}{d\alpha} & I_{52} &= C_5(0) \end{aligned} \right\} \quad (7)$$

Here, the following relations exist between the coefficients $a_m[i]$, and $c_m[i]$:

$$\left. \begin{aligned} a_{3(1)} &= v C_3(0) & C_3(0) &= \frac{h(h+2)}{2(1+h)^2} & C_4(1) &= v a_4(2) \\ a_4(2) &= -\frac{h(h+2)}{2(1+h)} & C_5(0) &= v a_5(1) & a_5(1) &= v \end{aligned} \right\} \quad (8)$$

Taking into account these relations, the system(6) is converted to the form:

$$\left[\begin{aligned} &\sqrt{1 + \left(\frac{dh}{d\alpha}\right)^2} P_{\alpha} = \frac{dh}{d\alpha} \left(\frac{du^0}{d\alpha} - v w^0 \right) - a_4(2) \left(\frac{d^2 u^0}{d\alpha^2} - v \frac{dw^0}{d\alpha} \right) \\ &\sqrt{1 + \left(\frac{dh}{d\alpha}\right)^2} P_{\gamma} = \frac{dh}{d\alpha} \left(\frac{d^2 u^0}{d\alpha^2} - v \frac{dw^0}{d\alpha} \right) a_4(2) - C_3(0) \left(v \frac{du^0}{d\alpha} - w^0 \right) \end{aligned} \right] \quad (9)$$

Let us consider the case when the forces acting on the external surface have only a vertical component, i.e., let us put $P_{\alpha} = 0$. To find this solution,

assuming in the system(9) P_{α} and $W^0 = \varphi$
 $\frac{du^0}{d\alpha} = -v\varphi$, we identically satisfy the first equation.

The second equation will take the form:

$$\sqrt{1 + \left(\frac{dh}{d\alpha}\right)^2} P_{\gamma} = (1 - v^2) \bar{C}_3(0) \varphi \quad (10)$$

$$\varphi = -\frac{P_{\gamma}}{1-v^2} \frac{\sqrt{1 + \left(\frac{dh}{d\alpha}\right)^2}}{\bar{C}_3(0)} \quad (11)$$

Accordingly, the initial function W^0 and the first derivative of the initial function $\frac{du^0}{d\alpha}$ are determined by the following formulas:

$$\left[\begin{aligned} \frac{du^0}{d\alpha} &= -\frac{v P_{\gamma}}{1-v^2} \frac{\sqrt{1 + \left(\frac{dh}{d\alpha}\right)^2}}{\bar{C}_3(0)} \\ W^0 &= \frac{P_{\gamma}}{1-v^2} \frac{\sqrt{1 + \left(\frac{dh}{d\alpha}\right)^2}}{\bar{C}_3(0)} \end{aligned} \right] \quad (12)$$

Substituting expressions (12) and (7) in the formulas of the main relations of the MNF, we obtain the final expressions for the values that characterize the VAT:

$$\left[\begin{aligned} W(\alpha, \gamma) &= (1 + \gamma) \varphi - (1 + v) \frac{\gamma(\gamma+2)}{2(1+\gamma)} \varphi \\ \frac{\sigma_{\gamma}(\alpha, \gamma)}{E} &= (1 - v^2) \frac{\gamma(\gamma+2)}{2(1+\gamma)^2} \varphi \\ \frac{\sigma_{\gamma}(\alpha, \gamma)}{E} &= (1 - v^2) \left(1 + \frac{1}{(1+\gamma)^2} \right) \varphi \\ \sigma_{\alpha} &= \tau_{\alpha\gamma} = 0 \end{aligned} \right] \quad (13)$$

In conclusion, we present calculation formulas for some special cases of the shape of the outer surface of the shell.

1. A shell whose relative thickness is a linear function of the axial coordinate α ,

i.e. $h(\alpha) = h(1 - k \alpha)$ where $K = \tan \theta$ is the tangent of the angle of inclination of the outer side surface relative to the axial coordinate α (figure 2).

In this case:

$$\begin{aligned} \frac{dh}{d\alpha} &= -hk, \quad P_{\gamma} = -\frac{P}{E}, \quad P_{\alpha} = 0 \\ \varphi &= -\frac{P}{E(1-v^2)} \sqrt{1 + h^2 k^2} \frac{2(1+h(\alpha))^2}{h(\alpha)(h(\alpha)+2)} \end{aligned}$$

For the desired functions, we have:

$$\begin{aligned} W(\alpha, \gamma) &= \frac{P}{E(1-v^2)} \sqrt{1 + h^2 k^2} (1 + \gamma - \\ &(1 + v) \frac{\gamma(\gamma+2)}{2(1+\gamma)^2} \frac{2(1+h(\alpha))}{h(\alpha)(h(\alpha)+2)} \end{aligned}$$

$$\sigma_{\gamma}(\alpha, \gamma) = -P \sqrt{1 + h^2 k^2} \frac{\gamma(\gamma+2)}{(1+\gamma)^2} \frac{(1+h(\alpha))^2}{h(\alpha)(h(\alpha)+2)}$$

$$\begin{aligned} \sigma_{\beta}(\alpha, \gamma) &= \\ &-P \sqrt{1 + h^2 k^2} \left[1 + \frac{1}{(1+\gamma)^2} \right] \frac{(1+h(\alpha))^2}{h(\alpha)(h(\alpha)+2)} \end{aligned}$$

$$\sigma_{\alpha}(\alpha, \gamma) = \tau_{\alpha\gamma}(\alpha, \gamma) = 0$$

2. A shell whose relative thickness varies according

to the hyperbolic law, i.e. $h(\alpha) = \frac{1}{1+\alpha}$ (Fig.3).

Similarly, we define:

$$\frac{dh}{d\alpha} = -\frac{h}{(1+\alpha)^2}, \quad P_{\gamma} = -\frac{P}{E}, \quad P_{\alpha} = 0$$

$$\varphi = -\frac{P}{E(1-v^2)} \sqrt{1 + \frac{h^2}{(1+\alpha)^4}} \frac{2(1+h(\alpha))^2}{h(\alpha)(h(\alpha)+2)}$$

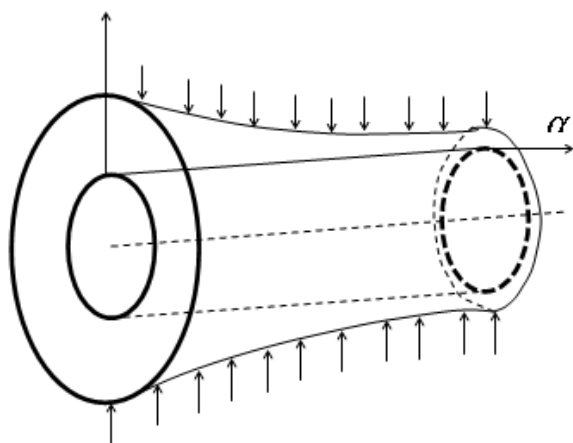


Figure 3

The desired functions are determined by relations(13) after substituting the expression for φ in them.

3. Shell, the thickness of which varies according to a parabolic law, i.e.

$$h(\alpha) = h(1 - k \alpha^2)$$

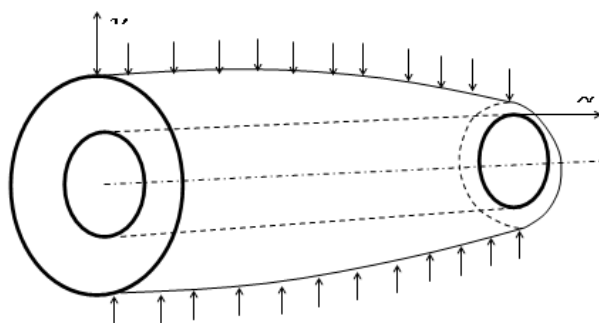


Figure 4

$$\frac{dh}{d\alpha} = -2hk\alpha, \quad P_Y = -\frac{P}{E}, \quad P_\alpha = 0$$

$$\varphi = -\frac{P}{E(1-\nu^2)} \sqrt{1 + 4h^2k^2\alpha^2} \frac{2(1+h(\alpha))^2}{h(\alpha)(h(\alpha)+2)}$$

As in the previous cases. $\sigma_\alpha, \sigma_\beta$, and the displacement W are defined by relations (13) with the expression support φ .

Note that for a constant thickness

$h(\alpha) = \text{Const}$, all the results obtained coincide with the known lame relations.

When using the results obtained, it should be borne in mind that the given calculation formulas are approximate. The simplicity of the obtained dependencies makes it possible to use them for estimated preliminary calculations.

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